



## FW250R1 and FW300R1 Power Modules: dc-dc Converters; 36 to 75 Vdc Input, 28 Vdc Output; 250 W to 300 W

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The FW250R1 and FW300R1 Power Modules use advanced, surface-mount technology and deliver high-quality, compact, dc-dc conversion at an economical price.

### Applications

- Redundant and distributed power architectures

### Options

- Heat sink available for extended operation

### Description

The FW250R1 and FW300R1 Power Modules are dc-dc converters that operate over an input voltage range of 36 Vdc to 75 Vdc and provide a precisely regulated dc output. The outputs are fully isolated from the inputs, allowing versatile polarity configurations and grounding connections. The modules have maximum power ratings from 250 W to 300 W at a typical full-load efficiency of 90.5%.

Two or more modules may be paralleled with forced load sharing for redundant or enhanced power applications. The package, which mounts on a printed-circuit board, accommodates a heat sink for high-temperature applications.

\* *UL* is a registered trademark of Underwriters Laboratories, Inc.

† *CSA* is a registered trademark of Canadian Standards Association.

‡ This product is intended for integration into end-use equipment. All the required procedures for CE marking of end-use equipment should be followed. (The CE mark is placed on selected products.)

### Features

- Size: 61.0 mm x 116.8 mm x 13.5 mm (2.40 in. x 4.60 in. x 0.53 in.)
- Wide input voltage range
- High efficiency: 90.5% typical
- Parallel operation with load sharing
- Output voltage set-point adjustment (trim)
- Thermal protection
- Synchronization
- Power good signal
- Current monitor
- Output overvoltage and overcurrent protection
- Constant frequency
- Case ground pin
- Input-to-output isolation
- Remote sense
- Remote on/off
- Short-circuit protection
- Output overvoltage clamp
- *UL*\* Recognized, *CSA*† Certified, VDE Licensed
- CE mark meets 73/23/EEC and 93/68/EEC directives‡

## Absolute Maximum Ratings

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only. Functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect device reliability.

Parameter	Symbol	Min	Max	Unit
Input Voltage: Continuous	$V_I$	—	80	Vdc
Transient (100 ms)	$V_{I, trans}$	—	100	Vdc
I/O Isolation Voltage	—	—	1500	V
Operating Case Temperature (See Thermal Considerations section and Figure 18.)	$T_C$	-40	100	°C
Storage Temperature	$T_{stg}$	-55	125	°C

## Electrical Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

**Table 1. Input Specifications**

Parameter	Symbol	Min	Typ	Max	Unit
Operating Input Voltage	$V_I$	36	48	75	Vdc
Maximum Input Current ( $V_I = 0$ V to 75 V): FW250R1	$I_{I, max}$	—	—	12	A
FW300R1	$I_{I, max}$	—	—	12	A
Inrush Transient	$i^2t$	—	—	2.0	A <sup>2</sup> s
Input Reflected-ripple Current, Peak-to-peak (5 Hz to 20 MHz, 12 $\mu$ H source impedance; see Figure 8.)	—	—	10	—	mAp-p
Input Ripple Rejection (120 Hz)	—	—	60	—	dB

## Fusing Considerations

**CAUTION: This power module is not internally fused. An input line fuse must always be used.**

This encapsulated power module can be used in a wide variety of applications, ranging from simple stand-alone operation to an integrated part of a sophisticated power architecture. To preserve maximum flexibility, internal fusing is not included; however, to achieve maximum safety and system protection, always use an input line fuse. The safety agencies require a normal-blow, dc fuse with a maximum rating of 20 A (see Safety Considerations section). Based on the information provided in this data sheet on inrush energy and maximum dc input current, the same type of fuse with a lower rating can be used. Refer to the fuse manufacturer's data for further information.

## Electrical Specifications (continued)

**Table 2. Output Specifications**

Parameter	Symbol	Min	Typ	Max	Unit
Output Voltage (Over all operating input voltage, resistive load, and temperature conditions until end of life; see Figure 9 and Feature Descriptions.)	$V_o$	27.16	—	28.84	Vdc
Output Voltage Set Point ( $V_i = 48$ V; $I_o = I_{o, \max}$ ; $T_c = 25$ °C)	$V_{o, \text{set}}$	27.45	—	28.55	Vdc
Output Regulation: Line ( $V_i = 36$ V to 75 V) Load ( $I_o = I_{o, \min}$ to $I_{o, \max}$ ) Temperature ( $T_c = -40$ °C to $+100$ °C)	— — —	— — —	0.01 0.05 100	0.1 0.2 300	% % mV
Output Ripple and Noise Voltage (See Figures 4 and 10.): RMS Peak-to-peak (5 Hz to 20 MHz)	— —	— —	— —	50 100	mVrms mVp-p
Output Current (At $I_o < I_{o, \min}$ , the modules may exceed output ripple specifications.): FW250R1 FW300R1	$I_o$ $I_o$	0.3 0.3	— —	9 10.7	A A
Output Current-limit Inception ( $V_o = 90\%$ of $V_{o, \text{set}}$ ; see Feature Descriptions.)	$I_{o, \text{cli}}$	103	—	130	% $I_{o, \max}$
Output Short-circuit Current ( $V_o = 1.0$ V; indefinite duration, no hiccup mode; see Figure 2.)	—	—	—	150	% $I_{o, \max}$
External Load Capacitance (electrolytic, total for one unit or multiple paralleled units): FW250R1 FW300R1	— —	330 330	— —	5,000 5,000	$\mu$ F $\mu$ F
Efficiency ( $V_i = 48$ V; $I_o = I_{o, \max}$ ; $T_c = 25$ °C; see Figures 3 and 9.): FW250R1 FW300R1	$\eta$ $\eta$	88.5 88.5	90.5 90.5	— —	% %
Dynamic Response ( $\Delta I_o/\Delta t = 1$ A/10 $\mu$ s, $V_i = 48$ V, $T_c = 25$ °C; see Figures 5 and 6.): Load Change from $I_o = 50\%$ to $75\%$ of $I_{o, \max}$ : Peak Deviation Settling Time ( $V_o < 10\%$ of peak deviation) Load Change from $I_o = 50\%$ to $25\%$ of $I_{o, \max}$ : Peak Deviation Settling Time ( $V_o < 10\%$ of peak deviation)	— — — —	— — — —	250 200 250 200	— — — —	mV $\mu$ s mV $\mu$ s

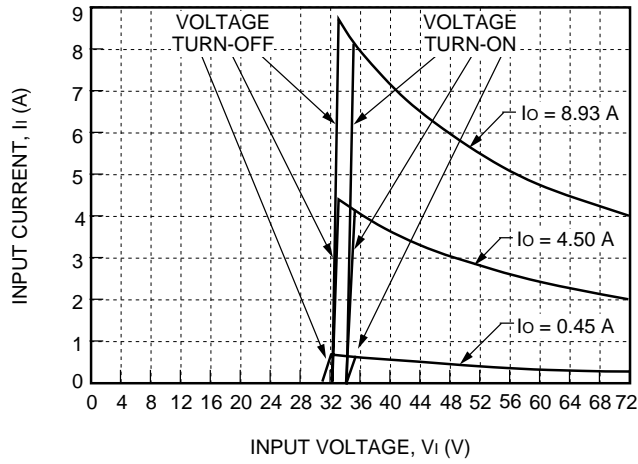
**Table 3. Isolation Specifications**

Parameter	Min	Typ	Max	Unit
Isolation Capacitance	—	1700	—	pF
Isolation Resistance	10	—	—	M $\Omega$



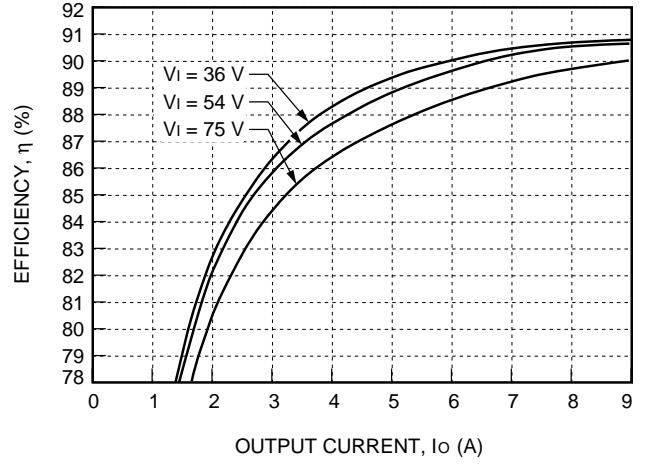
### Characteristic Curves

The following figures provide typical characteristics for the FW250R1 power modules.



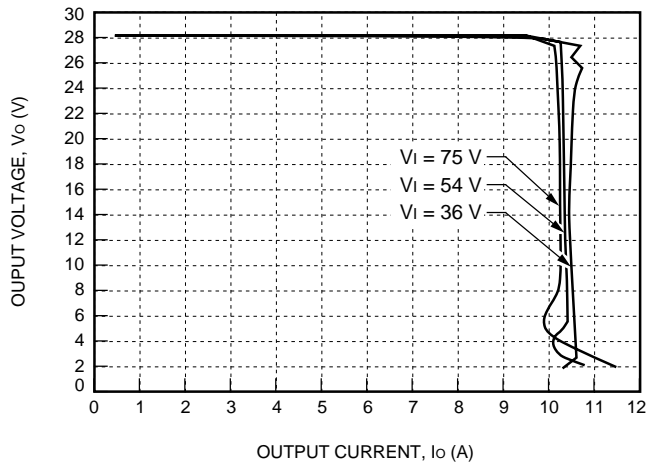
8-1713 (C)

Figure 1. Typical FW250R1 Input Characteristics at Room Temperature



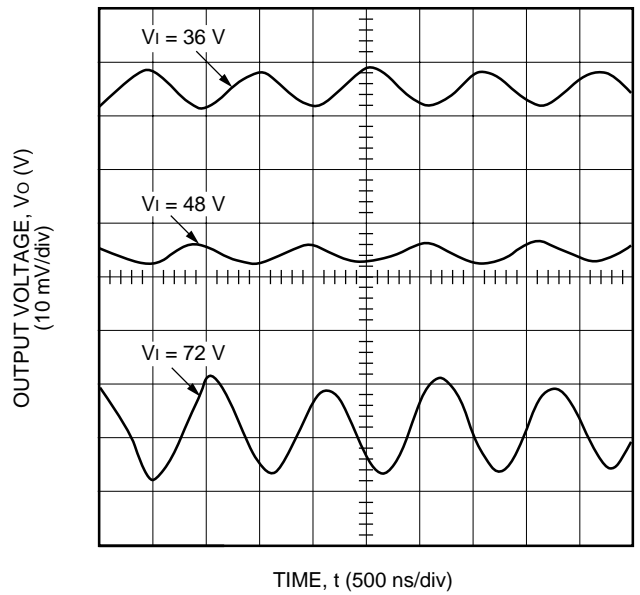
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Figure 3. Typical FW250R1 Efficiency vs. Output Current at Room Temperature



8-1714 (C)

Figure 2. Typical FW250R1 Output Characteristics at Room Temperature



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Figure 4. Typical FW250R1 Output Ripple Voltage at Room Temperature, 48 V Input, and Full Load Output

Characteristic Curves (continued)

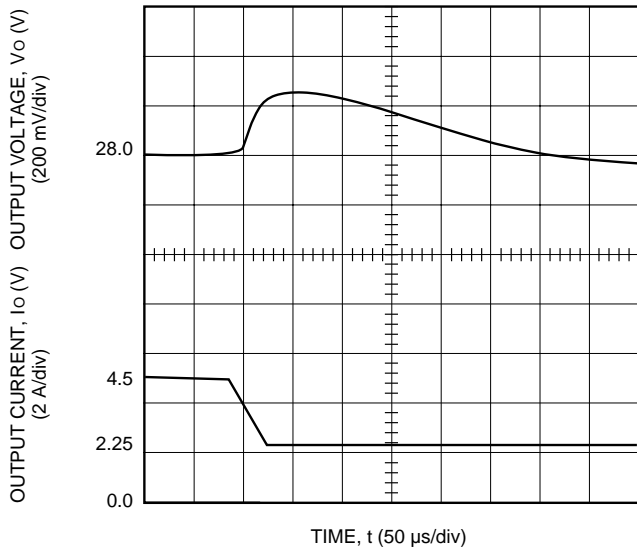


Figure 5. Typical FW250R1 Transient Response to Step Decrease in Load from 50% to 25% of Full Load at Room Temperature and 48 V Input (Waveform Averaged to Eliminate Ripple Component.)

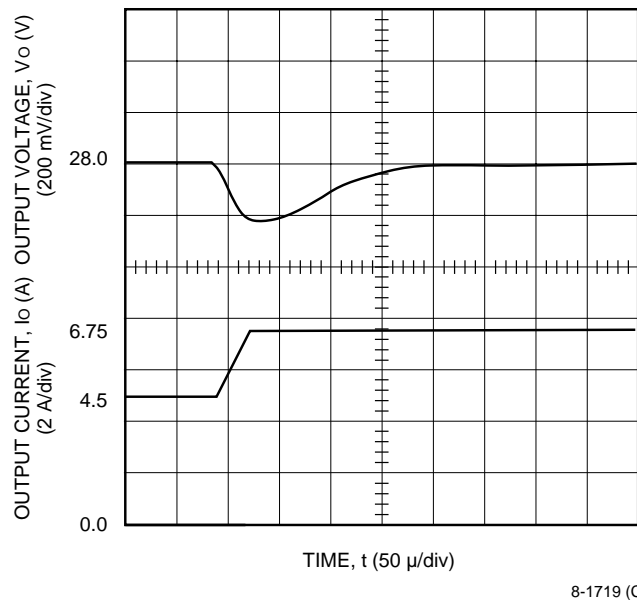


Figure 6. Typical FW250R1 Transient Response to Step Increase in Load from 50% to 75% of Full Load at Room Temperature and 48 V Input (Waveform Averaged to Eliminate Ripple Component.)

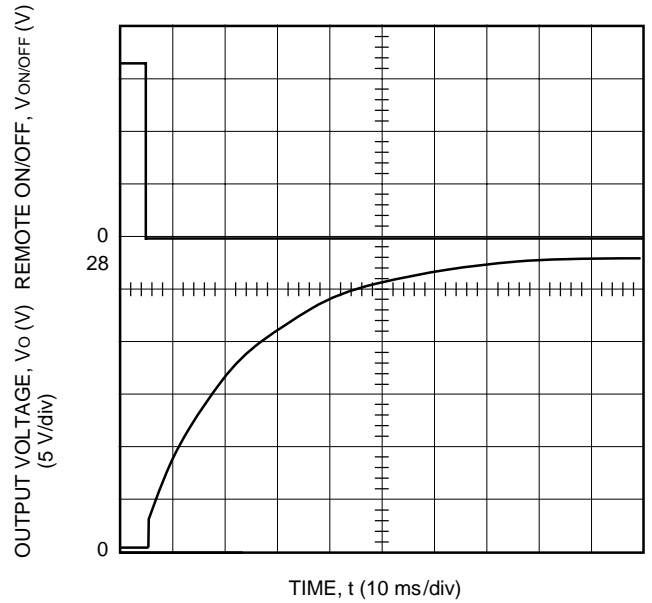
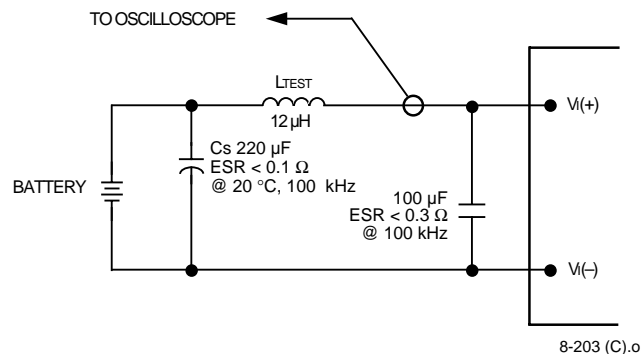


Figure 7. Typical FW250R1 Start-Up Transient at Room Temperature, 48 V Input, and Full Load

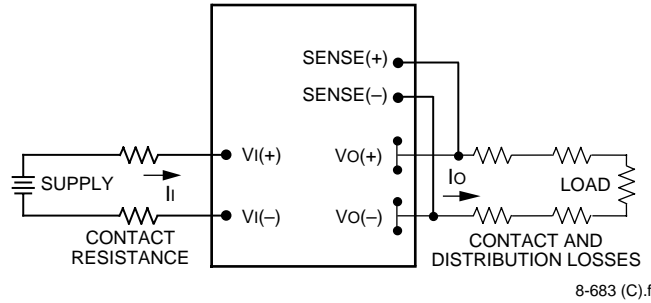
Test Configurations



Note: Measure input reflected-ripple current with a simulated source inductance ( $L_{TEST}$ ) of 12  $\mu$ H. Capacitor  $C_s$  offsets possible battery impedance. Measure current as shown above.

Figure 8. Input Reflected-Ripple Test Setup

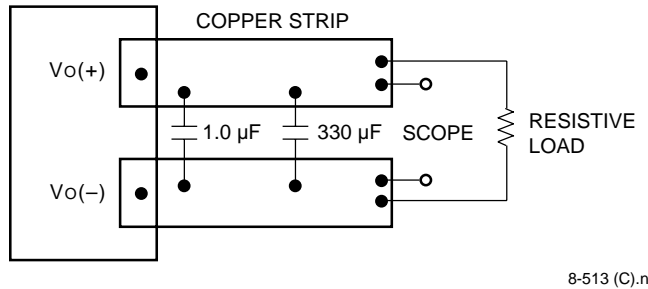
## Test Configurations (continued)



Note: All measurements are taken at the module terminals. When socketing, place Kelvin connections at module terminals to avoid measurement errors due to socket contact resistance.

$$\eta = \left( \frac{[V_{O(+)} - V_{O(-)}] I_o}{[V_{I(+)} - V_{I(-)}] I_i} \right) \times 100$$

**Figure 9. Output Voltage and Efficiency Measurement Test Setup**



Note: Use a 0.1 µF ceramic capacitor and a 330 µF aluminum or tantalum capacitor. The 330 µF capacitor is needed for stability. Scope measurement should be made using a BNC socket. Position the load between 50 mm and 76 mm (2 in. and 3 in.) from the module.

**Figure 10. Peak-to-Peak Output Noise Measurement Test Setup**

## Design Considerations

### Input Source Impedance

The power module should be connected to a low ac-impedance input source. Highly inductive source impedances can affect the stability of the power module. For the test configuration in Figure 8, a 100 µF electrolytic capacitor (ESR < 0.3 Ω at 100 kHz) mounted close to the power module helps ensure stability of the unit. For other highly inductive source impedances, consult the factory for further application guidelines.

### Safety Considerations

For safety-agency approval of the system in which the power module is used, the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standard, i.e., UL-1950, CSA 22.2-950, and EN60950.

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV), one of the following must be true:

- All inputs are SELV and floating, with the output also floating.
- All inputs are SELV and grounded, with the output also grounded.
- Any non-SELV input must be provided with reinforced insulation from any other hazardous voltages, including the ac mains, and must have a SELV reliability test performed on it in combination with the converters. Inputs must meet SELV requirements.

If the input meets extra-low voltage (ELV) requirements, then the converter's output is considered ELV.

The input to these units is to be provided with a maximum 20 A normal-blow fuse in the ungrounded lead.

## Electrical Descriptions

### Current Limit

To provide protection in a fault (output overload) condition, the unit is equipped with internal current-limiting circuitry and can endure current limiting for an unlimited duration. At the point of current-limit inception, the unit shifts from voltage control to current control. If the output voltage is pulled very low during a severe fault, the current-limit circuit can exhibit either foldback or tailout characteristics (output-current decrease or increase). The unit operates normally once the output current is brought back into its specified range.

## Feature Descriptions

### Remote On/Off

To turn the power module on and off, the user must supply a switch to control the voltage between the on/off terminal and the VI(-) terminal ( $V_{on/off}$ ). The switch can be an open collector or equivalent (see Figure 11). A logic low is  $V_{on/off} = 0$  V to 1.2 V, during which the module is on. The maximum  $I_{on/off}$  during a logic low is 1 mA. The switch should maintain a logic-low voltage while sinking 1 mA.

During a logic high, the maximum  $V_{on/off}$  generated by the power module is 15 V. The maximum allowable leakage current of the switch at  $V_{on/off} = 15$  V is 50  $\mu$ A.

If not using the remote on/off feature, short the ON/OFF pin to VI(-).

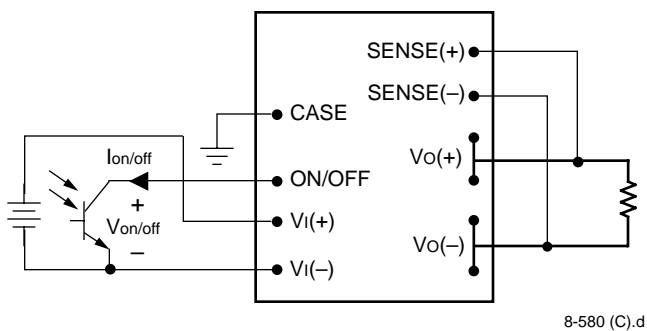


Figure 11. Remote On/Off Implementation

### Remote Sense

Remote sense minimizes the effects of distribution losses by regulating the voltage at the remote-sense connections. The voltage between the remote-sense pins and the output terminals must not exceed the output voltage sense range given in the Feature Specifications table, i.e.:

$$[V_o(+)-V_o(-)]-[SENSE(+)-SENSE(-)] \leq 0.5 \text{ V}$$

The voltage between the  $V_o(+)$  and  $V_o(-)$  terminals must not exceed the minimum value indicated in the output overvoltage shutdown section of the Feature Specifications table. This limit includes any increase in voltage due to remote-sense compensation and output voltage set-point adjustment (trim), see Figure 12.

If not using the remote-sense feature to regulate the output at the point of load, connect SENSE(+) to  $V_o(+)$  and SENSE(-) to  $V_o(-)$  at the module.

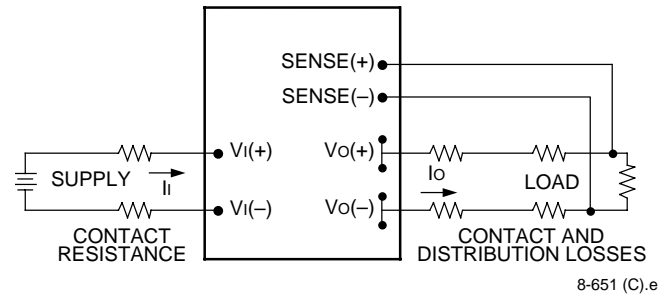


Figure 12. Effective Circuit Configuration for Single-Module Remote-Sense Operation

### Output Voltage Set-Point Adjustment (Trim)

Output voltage trim allows the user to increase or decrease the output voltage set point of a module. This is accomplished by connecting an external resistor between the TRIM pin and either the SENSE(+) or SENSE(-) pins. With an external resistor between the TRIM and SENSE(-) pins ( $R_{adj-down}$ ), the output voltage set point ( $V_{o, adj}$ ) decreases (see Figure 13). The following equation determines the required external-resistor value to obtain a percentage output voltage change of  $\Delta\%$ .

$$R_{adj-down} = \left( \frac{205}{\Delta\%} - 2.255 \right) \text{ k}\Omega$$

The test results for this configuration are displayed in Figure 14. This figure applies to all output voltages.

With an external resistor connected between the TRIM and SENSE(+) pins ( $R_{adj-up}$ ), the output voltage set point ( $V_{o, adj}$ ) increases (see Figure 15).

**Note:** The output voltage of this module may be increased to a maximum of 0.5 V. The 0.5 V is the combination of both the remote sense and the output voltage set-point adjustment (trim). Do not exceed 28.5 V between the  $V_o(+)$  and  $V_o(-)$  terminals.

The following equation determines the required external-resistor value to obtain a percentage output voltage change of  $\Delta\%$ .

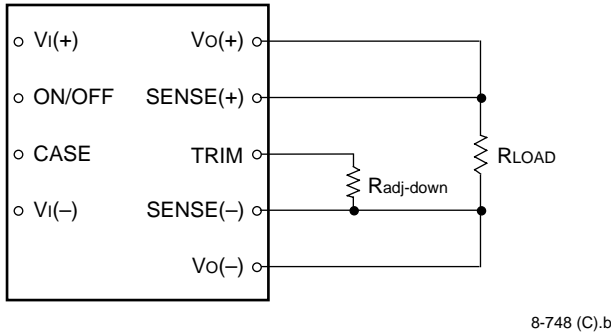
**Only trim up to 0.5 V maximum. See note above.**

**Feature Descriptions** (continued)

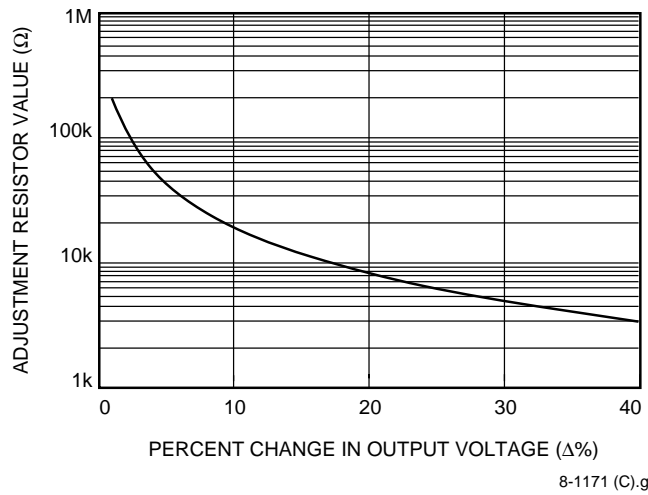
**Output Voltage Set-Point Adjustment (Trim)**  
(continued)

The test results for this configuration are displayed in Figure 16.

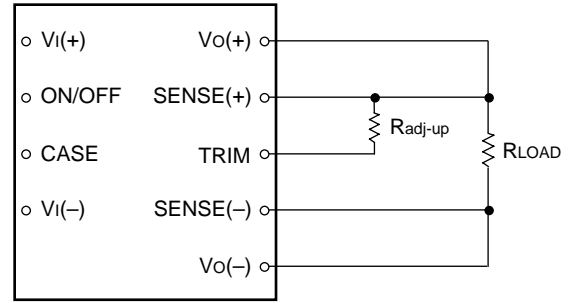
If not using the trim feature, leave the TRIM pin open.



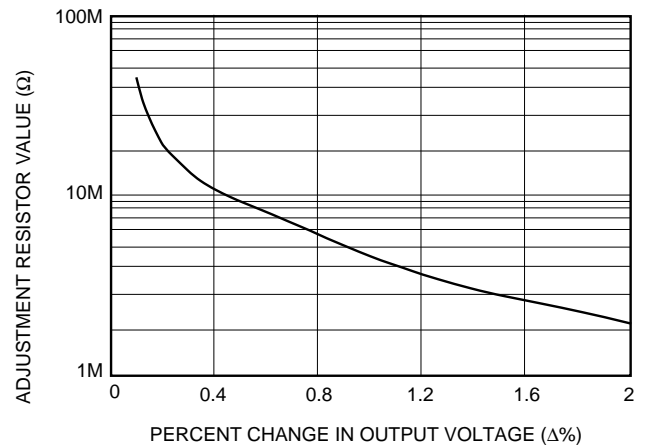
**Figure 13. Circuit Configuration to Decrease Output Voltage**



**Figure 14. Resistor Selection for Decreased Output Voltage**



**Figure 15. Circuit Configuration to Increase Output Voltage**



**Figure 16. Resistor Selection for Increased Output Voltage**

**Output Overvoltage Protection**

The output voltage is monitored at the Vo(+) and Vo(-) pins of the module. If the voltage at these pins exceeds the value indicated in the Feature Specifications table, the module will shut down and latch off. Recovery from latched shutdown is accomplished by cycling the dc input power off for at least 1.0 s or toggling the primary referenced on/off signal for at least 1.0 s.

## Feature Descriptions (continued)

### Output Current Monitor

The CURRENT MON pin provides a dc voltage proportional to the dc output current of the module given in the Feature Specifications table. For example, on the FW250R1, the V/A ratio is set at 370 mV/A  $\pm$  10% @ 70 °C case. At a full load current of 9 A, the voltage on the CURRENT MON pin is 3.33 V. The current monitor signal is referenced to the SENSE(–) pin on the secondary and is supplied from a source impedance of approximately 2 k $\Omega$ . It is recommended that the CURRENT MON pin be left open when not in use, although no damage will result if the CURRENT MON pin is shorted to secondary ground. Directly driving the CURRENT MON pin with an external source will detrimentally affect operation of the module and should be avoided.

### Synchronization

Any module can be synchronized to any other module or to an external clock using the SYNC IN or SYNC OUT pins. The modules are not designed to operate in a master/slave configuration; that is, if one module fails, the other modules will continue to operate.

#### SYNC IN Pin

This pin can be connected either to an external clock or directly to the SYNC OUT pin of another FW250x or FW300x module.

If an external clock signal is applied to the SYNC IN pin, the signal must be a 500 kHz ( $\pm$ 50 kHz) square wave with a 4 V<sub>p-p</sub> amplitude. Operation outside this frequency band will detrimentally affect the performance of the module and must be avoided.

If the SYNC IN pin is connected to the SYNC OUT pin of another module, the connection should be as direct as possible, and the V<sub>I</sub>(–) pins of the modules must be shorted together.

Unused SYNC IN pins should be tied to V<sub>I</sub>(–). If the SYNC IN pin is unused, the module will operate from its own internal clock.

#### SYNC OUT Pin

This pin contains a clock signal referenced to the V<sub>I</sub>(–) pin. The frequency of this signal will equal either the module's internal clock frequency or the frequency established by an external clock applied to the SYNC IN pin.

When synchronizing several modules together, the modules can be connected in a daisy-chain fashion where the SYNC OUT pin of one module is connected to the SYNC IN pin of another module. Each module in the chain will synchronize to the frequency of the first module in the chain.

To avoid loading effects, ensure that the SYNC OUT pin of any one module is connected to the SYNC IN pin of only one module. Any number of modules can be synchronized in this daisy-chain fashion.

### Overtemperature Shutdown

To provide protection in a fault condition, the unit is equipped with an overtemperature shutdown circuit. The shutdown circuit will not engage unless the unit is operated above the maximum case temperature. Recovery from overtemperature shutdown is accomplished by cycling the dc input power off for at least 1.0 s or toggling the primary referenced on/off signal for at least 1.0 s.

### Forced Load Sharing (Parallel Operation)

For either redundant operation or additional power requirements, the power modules can be configured for parallel operation with forced load sharing (see Figure 17). For a typical redundant configuration, Schottky diodes or an equivalent should be used to protect against short-circuit conditions. Because of the remote sense, the forward-voltage drops across the Schottky diodes do not affect the set point of the voltage applied to the load. For additional power requirements, where multiple units are used to develop combined power in excess of the rated maximum, the Schottky diodes are not needed.

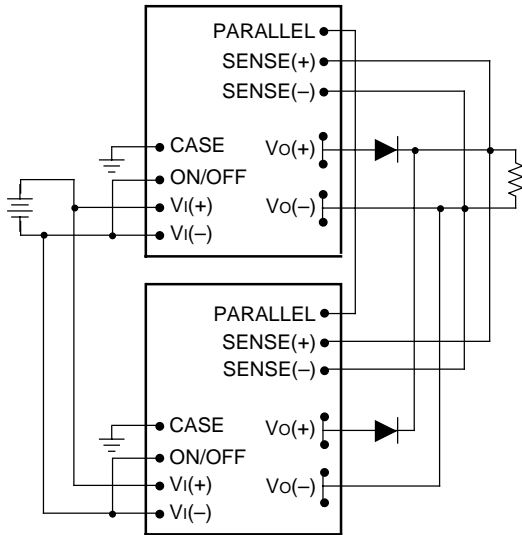
Good layout techniques should be observed for noise immunity. To implement forced load sharing, the following connections must be made:

- The parallel pins of all units must be connected together. The paths of these connections should be as direct as possible.
- All remote-sense pins should be connected to the power bus at the same point, i.e., connect all SENSE(+) pins to the (+) side of the power bus at the same point and all SENSE(–) pins to the (–) side of the power bus at the same point. Close proximity and directness are necessary for good noise immunity.

When not using the parallel feature, leave the PARALLEL pin open.

Feature Descriptions (continued)

Forced Load Sharing (Parallel Operation)  
(continued)



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Figure 17. Wiring Configuration for Redundant Parallel Operation

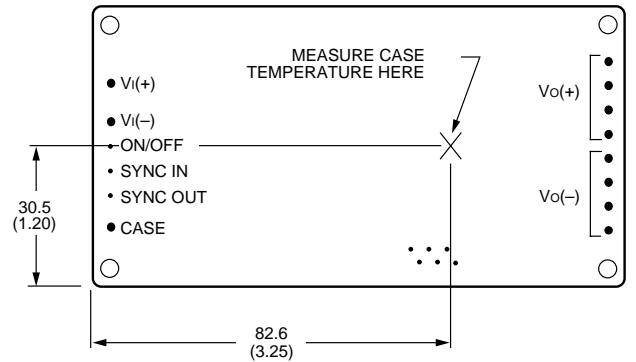
Power Good Signal

The PWR GOOD pin provides an open-drain signal (referenced to the SENSE(-) pin) that indicates the operating state of the module. A low impedance (<math><100 \Omega</math>) between PWR GOOD and SENSE(-) indicates that the module is operating. A high impedance (>1 M $\Omega$ ) between PWR GOOD and SENSE(-) indicates that the module is off or has failed. The PWR GOOD pin can be pulled up through a resistor to an external voltage to facilitate sensing. This external voltage level must not exceed 40 V, and the current into the PWR GOOD pin during the low-impedance state should be limited to 1 mA maximum.

Thermal Considerations

Introduction

The power modules operate in a variety of thermal environments; however, sufficient cooling should be provided to help ensure reliable operation of the unit. Heat-dissipating components inside the unit are thermally coupled to the case. Heat is removed by conduction, convection, and radiation to the surrounding environment. Proper cooling can be verified by measuring the case temperature. Peak temperature occurs at the position indicated in Figure 18.



8-1303 (C).a

Note: Top view, measurements shown in millimeters and (inches). Pin locations are for reference only.

Figure 18. Case Temperature Measurement Location

The temperature at this location should not exceed 100 °C. The maximum case temperature can be limited to a lower value for extremely high reliability. The output power of the module should not exceed the rated power for the module as listed in the Ordering Information table.

For additional information about these modules, refer to the Lucent Technologies *Thermal Management for FC- and FW-Series 250 W—300 W Board-Mounted Power Modules* Technical Note (TN96-009EPS).

Thermal Considerations (continued)

Heat Transfer Without Heat Sinks

Derating curves for forced-air cooling without a heat sink are shown in Figures 19 and 20. These curves can be used to determine the appropriate airflow for a given set of operating conditions. For example, if the unit with airflow along its length dissipates 20 W of heat, the correct airflow in a 40 °C environment is 1.0 m/s (200 ft./min.).

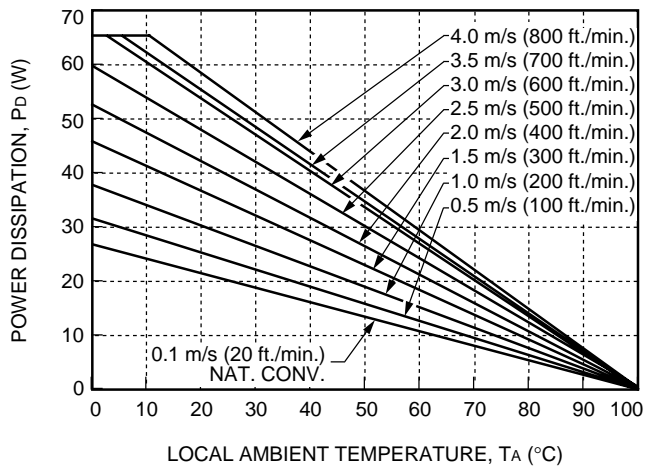


Figure 19. Convection Power Derating with No Heat Sink; Airflow Along Width (Transverse)

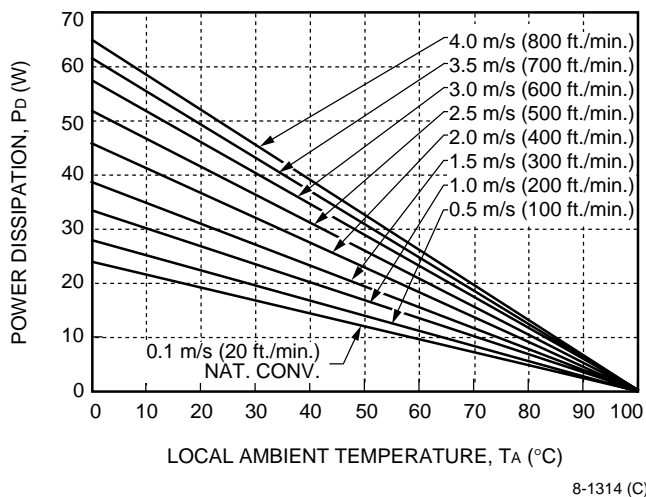


Figure 20. Convection Power Derating with No Heat Sink; Airflow Along Length (Longitudinal)

Heat Transfer with Heat Sinks

The power modules have through-threaded, M3 x 0.5 mounting holes, which enable heat sinks or cold plates to be attached to the module. The mounting torque must not exceed 0.56 N-m (5 in.-lb.). For the screw attachment from the pin side, the recommended hole size on the customer's PWB around the mounting holes is 0.130 ± 0.005 inches. If a larger hole is used, the mounting torque from the pin side must not exceed 0.25 N-m (2.2 in.-lbs.).

Thermal derating with heat sinks is expressed by using the overall thermal resistance of the module. Total module thermal resistance ( $\theta_{ca}$ ) is defined as the maximum case temperature rise ( $\Delta T_{c, max}$ ) divided by the module power dissipation ( $P_D$ ):

$$\theta_{ca} = \frac{\Delta T_{c, max}}{P_D} = \frac{(T_C - T_A)}{P_D}$$

The location to measure case temperature ( $T_c$ ) is shown in Figure 18. Case-to-ambient thermal resistance vs. airflow for various heat sink configurations is shown in Figure 21 and Figure 22. These curves were obtained by experimental testing of heat sinks, which are offered in the product catalog.

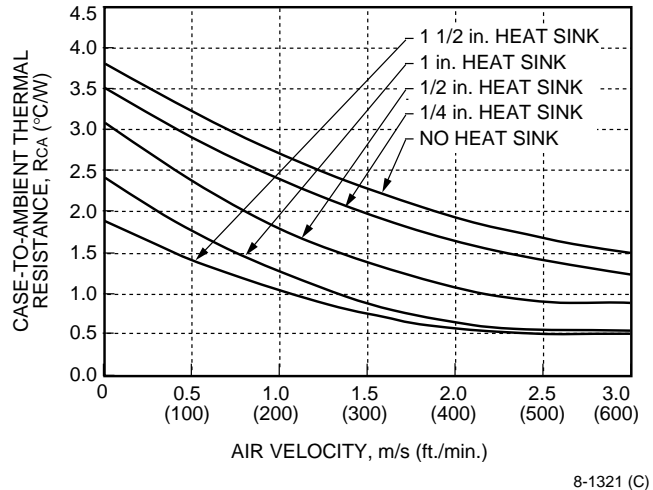
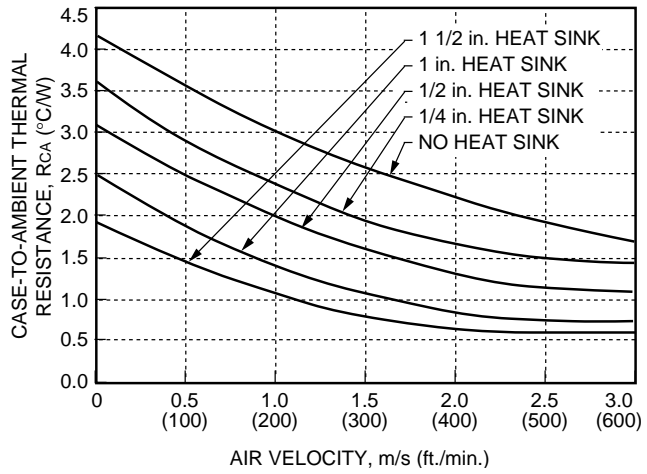


Figure 21. Case-to-Ambient Thermal Resistance Curves; Transverse Orientation

**Thermal Considerations** (continued)

**Heat Transfer with Heat Sinks** (continued)

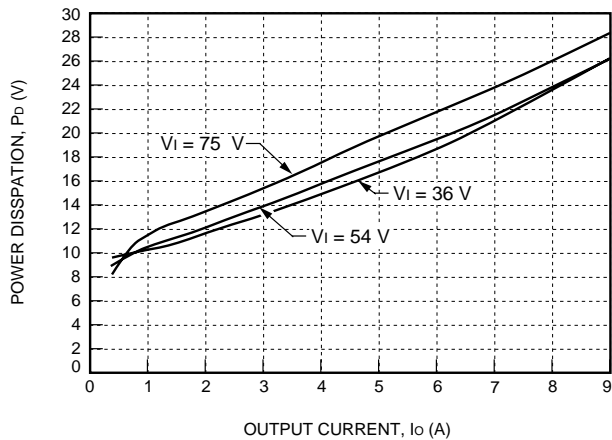


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**Figure 22. Case-to-Ambient Thermal Resistance Curves; Longitudinal Orientation**

These measured resistances are from heat transfer from the sides and bottom of the module as well as the top side with the attached heat sink; therefore, the case-to-ambient thermal resistances shown are generally lower than the resistance of the heat sink by itself. The module used to collect the data in Figures 21 and 22 had a thermal-conductive dry pad between the case and the heat sink to minimize contact resistance.

To choose a heat sink, determine the power dissipated as heat by the unit for the particular application. Figure 23 shows typical heat dissipation for a range of output currents and three voltages for the FW250R1.



8-1723 (C)

**Figure 23. FW250R1 Power Dissipation vs. Output Current**

**Example**

If an 85 °C case temperature is desired, what is the minimum airflow necessary? Assume the FW250R1 module is operating at nominal line and an output current of 9 A, maximum ambient air temperature of 40 °C, and the heat sink is 0.5 inch.

**Solution**

- Given:  $V_i = 54 \text{ V}$
- $I_o = 9 \text{ A}$
- $T_A = 40 \text{ }^\circ\text{C}$
- $T_C = 85 \text{ }^\circ\text{C}$
- Heat sink = 0.5 inch.

Determine  $P_D$  by using Figure 23:

$$P_D = 26 \text{ W}$$

Then solve the following equation:

$$\theta_{ca} = \left[ \frac{T_C - T_A}{P_D} \right]$$

$$\theta_{ca} = \left[ \frac{85 - 40}{26} \right]$$

$$\theta_{ca} = 1.73 \text{ }^\circ\text{C/W}$$

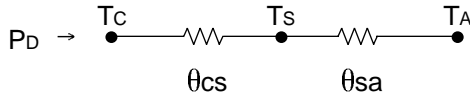
Use Figures 21 and 22 to determine air velocity for the 0.5 inch heat sink. The minimum airflow necessary for the FW250R1 module depends on heat sink fin orientation and is shown below:

- 1.1 m/s (220 ft./min.) (oriented along width)
- 2.0 m/s (400 ft./min.) (oriented along length)

**Thermal Considerations** (continued)

**Custom Heat Sinks**

A more detailed model can be used to determine the required thermal resistance of a heat sink to provide necessary cooling. The total module resistance can be separated into a resistance from case-to-sink ( $\theta_{cs}$ ) and sink-to-ambient ( $\theta_{sa}$ ) as shown in Figure 24.



8-1304 (C)

**Figure 24. Resistance from Case-to-Sink and Sink-to-Ambient**

For a managed interface using thermal grease or foils, a value of  $\theta_{cs} = 0.1 \text{ }^\circ\text{C/W}$  to  $0.3 \text{ }^\circ\text{C/W}$  is typical. The solution for heat sink resistance is:

$$\theta_{sa} = \left[ \frac{(T_C - T_A)}{P_D} \right] - \theta_{cs}$$

This equation assumes that all dissipated power must be shed by the heat sink. Depending on the user-defined application environment, a more accurate model, including heat transfer from the sides and bottom of the module, can be used. This equation provides a conservative estimate for such instances.

**Layout Considerations**

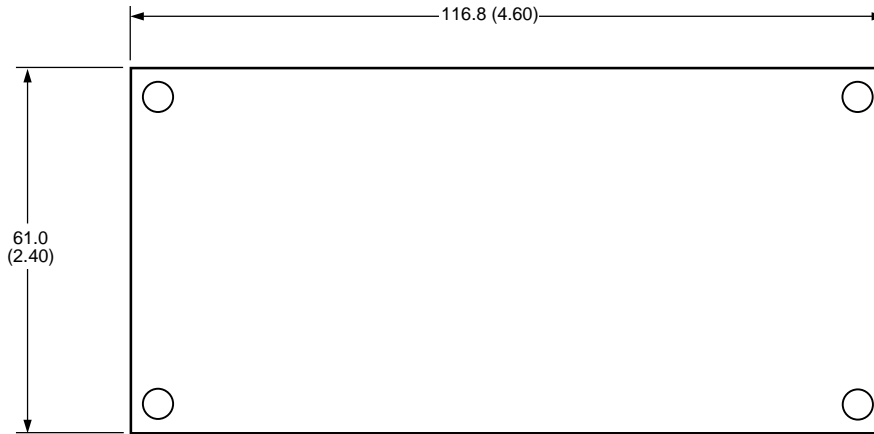
Copper paths must not be routed beneath the power module mounting inserts.

## Outline Diagram

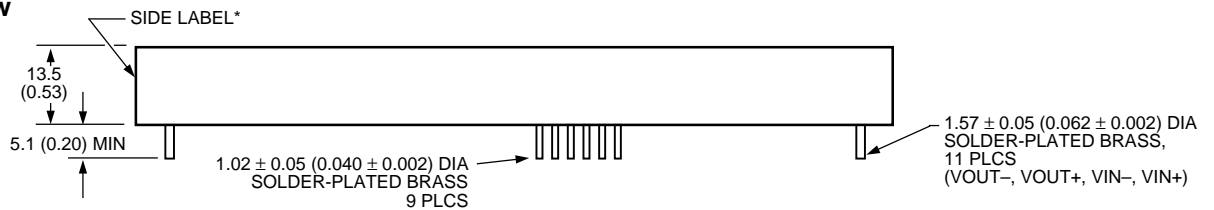
Dimensions are in millimeters and (inches).

Tolerances: x.x mm  $\pm$  0.5 mm (x.xx in.  $\pm$  0.02 in.),  
x.xx mm  $\pm$  0.25 mm (x.xxx in.  $\pm$  0.010 in.)

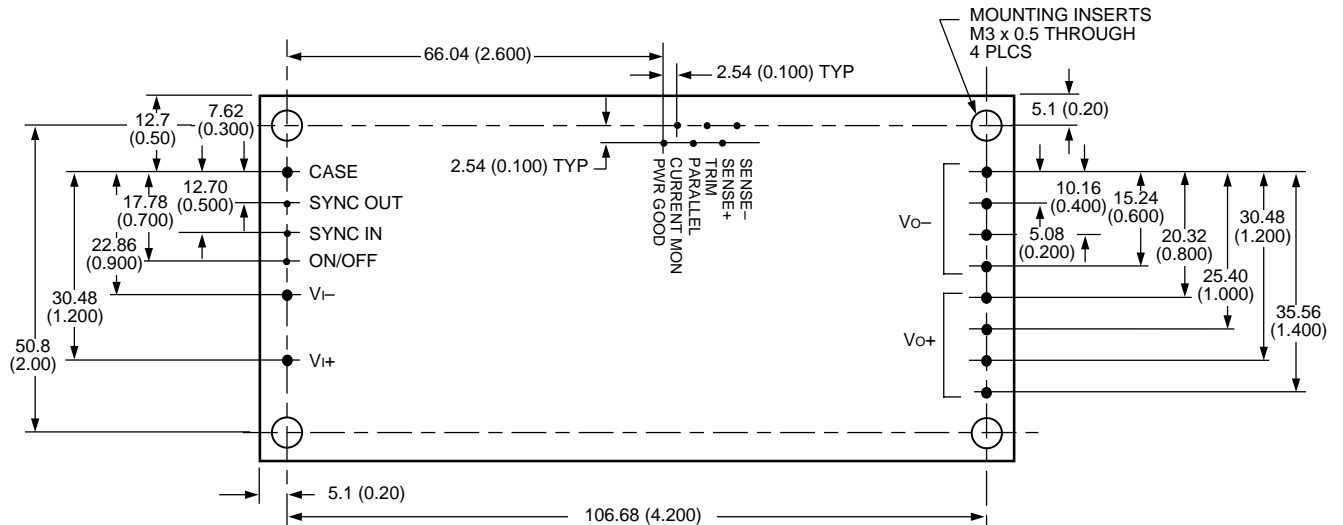
### Top View



### Side View



### Bottom View



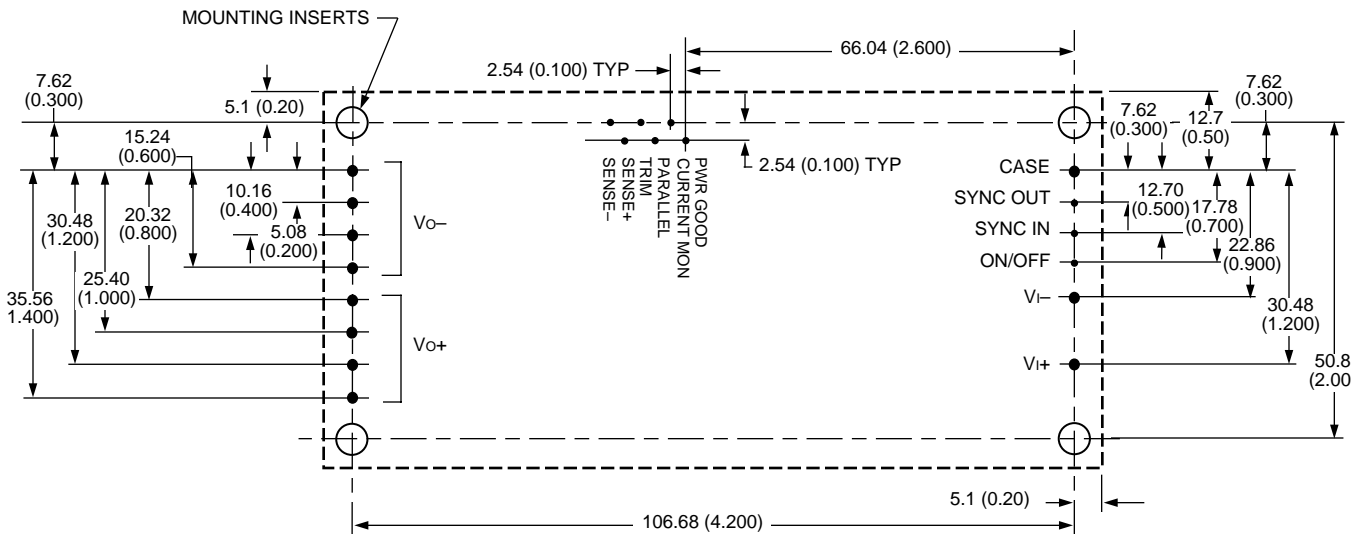
8-1650 (C)

\* Side label includes Lucent logo, product designation, safety agency markings, input/output voltage and current ratings, and bar code.

## Recommended Hole Pattern

Component-side footprint.

Dimensions are in millimeters and (inches).



8-1650 (C)

## Ordering Information

Input Voltage	Output Voltage	Output Power	Device Code	Comcode
48 V	28 V	250 W	FW250R1	107679029
48 V	28 V	300 W	FW300R1	107430332

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