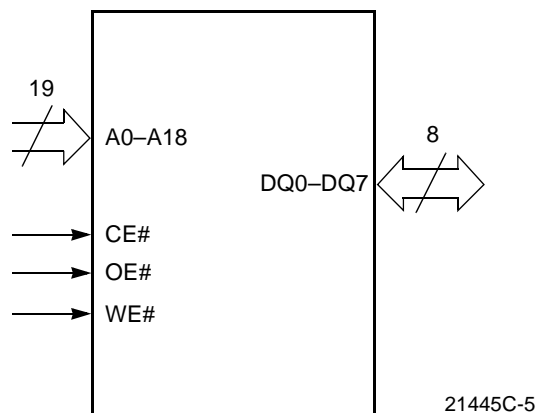


## PIN CONFIGURATION

A0–A18 = Address Inputs  
 DQ0–DQ7 = Data Input/Output  
 CE# = Chip Enable  
 WE# = Write Enable  
 OE# = Output Enable  
 V<sub>SS</sub> = Device Ground  
 V<sub>CC</sub> = +5.0 V single power supply  
 (see Product Selector Guide for device speed ratings and voltage supply tolerances)

## LOGIC SYMBOL



## ORDERING INFORMATION

### Standard Products

AMD standard products are available in several packages and operating ranges. The order number (Valid Combination) is formed by a combination of the following:

<b>Am29F040B</b>	<b>-55</b>	<b>E</b>	<b>C</b>	<b>B</b>	<b>OPTIONAL PROCESSING</b>
					Blank = Standard Processing
					B = Burn-In
					(Contact an AMD representative for more information)
					<b>TEMPERATURE RANGE</b>
					C = Commercial (0°C to +70°C)
					I = Industrial (–40°C to +85°C)
					E = Extended (–55°C to +125°C)
					<b>PACKAGE TYPE</b>
					P = 32-Pin Plastic DIP (PD 032)
					J = 32-Pin Rectangular Plastic Leaded Chip Carrier (PL 032)
					E = 32-Pin Thin Small Outline Package (TSOP) Standard Pinout (TS 032)
					F = 32-Pin Thin Small Outline Package (TSOP) Reverse Pinout (TSR032)
					<b>SPEED OPTION</b>
					See Product Selector Guide and Valid Combinations
					<b>DEVICE NUMBER/DESCRIPTION</b>
					Am29F040B
					4 Megabit (512 K x 8-Bit) CMOS 5.0 Volt-only Sector Erase Flash Memory
					5.0 V Read, Program, and Erase

Valid Combinations	
AM29F040B-55	JC, JI, JE, EC, EI, EE, FC, FI, FE
AM29F040B-70	
AM29F040B-90	PC, PI, PE, JC, JI, JE, EC, EI, EE, FC, FI, FE
AM29F040B-120	
AM29F040B-150	

### Valid Combinations

Valid Combinations list configurations planned to be supported in volume for this device. Consult the local AMD sales office to confirm availability of specific valid combinations and to check on newly released combinations.

## DEVICE BUS OPERATIONS

This section describes the requirements and use of the device bus operations, which are initiated through the internal command register. The command register itself does not occupy any addressable memory location. The register is composed of latches that store the commands, along with the address and data information

needed to execute the command. The contents of the register serve as inputs to the internal state machine. The state machine outputs dictate the function of the device. The appropriate device bus operations table lists the inputs and control levels required, and the resulting output. The following subsections describe each of these operations in further detail.

**Table 1. Am29F040B Device Bus Operations**

Operation	CE#	OE#	WE#	A0–A20	DQ0–DQ7
Read	L	L	H	A <sub>IN</sub>	D <sub>OUT</sub>
Write	L	H	L	A <sub>IN</sub>	D <sub>IN</sub>
CMOS Standby	V <sub>CC</sub> ± 0.5 V	X	X	X	High-Z
TTL Standby	H	X	X	X	High-Z
Output Disable	L	H	H	X	High-Z

**Legend:**

L = Logic Low = V<sub>IL</sub>, H = Logic High = V<sub>IH</sub>, V<sub>ID</sub> = 12.0 ± 0.5 V, X = Don't Care, D<sub>IN</sub> = Data In, D<sub>OUT</sub> = Data Out, A<sub>IN</sub> = Address In

**Note:** See the “Sector Protection/Unprotection” section. for more information.

### Requirements for Reading Array Data

To read array data from the outputs, the system must drive the CE# and OE# pins to V<sub>IL</sub>. CE# is the power control and selects the device. OE# is the output control and gates array data to the output pins. WE# should remain at V<sub>IH</sub>.

The internal state machine is set for reading array data upon device power-up, or after a hardware reset. This ensures that no spurious alteration of the memory content occurs during the power transition. No command is necessary in this mode to obtain array data. Standard microprocessor read cycles that assert valid addresses on the device address inputs produce valid data on the device data outputs. The device remains enabled for read access until the command register contents are altered.

See “Reading Array Data” for more information. Refer to the AC Read Operations table for timing specifications and to the Read Operations Timings diagram for the timing waveforms. I<sub>CC1</sub> in the DC Characteristics table represents the active current specification for reading array data.

### Writing Commands/Command Sequences

To write a command or command sequence (which includes programming data to the device and erasing sectors of memory), the system must drive WE# and CE# to V<sub>IL</sub>, and OE# to V<sub>IH</sub>.

An erase operation can erase one sector, multiple sectors, or the entire device. The Sector Address Tables

indicate the address space that each sector occupies. A “sector address” consists of the address bits required to uniquely select a sector. See the “Command Definitions” section for details on erasing a sector or the entire chip, or suspending/resuming the erase operation.

After the system writes the autoselect command sequence, the device enters the autoselect mode. The system can then read autoselect codes from the internal register (which is separate from the memory array) on DQ7–DQ0. Standard read cycle timings apply in this mode. Refer to the “Autoselect Mode” and “Autoselect Command Sequence” sections for more information.

I<sub>CC2</sub> in the DC Characteristics table represents the active current specification for the write mode. The “AC Characteristics” section contains timing specification tables and timing diagrams for write operations.

### Program and Erase Operation Status

During an erase or program operation, the system may check the status of the operation by reading the status bits on DQ7–DQ0. Standard read cycle timings and I<sub>CC</sub> read specifications apply. Refer to “Write Operation Status” for more information, and to each AC Characteristics section for timing diagrams.

### Standby Mode

When the system is not reading or writing to the device, it can place the device in the standby mode. In this mode, current consumption is greatly reduced, and the

outputs are placed in the high impedance state, independent of the OE# input.

The device enters the CMOS standby mode when the CE# pin is held at  $V_{CC} \pm 0.5$  V. (Note that this is a more restricted voltage range than  $V_{IH}$ .) The device enters the TTL standby mode when CE# is held at  $V_{IH}$ . The device requires the standard access time ( $t_{CE}$ ) before it is ready to read data.

If the device is deselected during erasure or programming, the device draws active current until the operation is completed.

$I_{CC3}$  in the DC Characteristics tables represents the standby current specification.

### Output Disable Mode

When the OE# input is at  $V_{IH}$ , output from the device is disabled. The output pins are placed in the high impedance state.

**Table 2. Sector Addresses Table**

Sector	A18	A17	A16	Address Range
SA0	0	0	0	00000h–0FFFFh
SA1	0	0	1	10000h–1FFFFh
SA2	0	1	0	20000h–2FFFFh
SA3	0	1	1	30000h–3FFFFh
SA4	1	0	0	40000h–4FFFFh
SA5	1	0	1	50000h–5FFFFh
SA6	1	1	0	60000h–6FFFFh
SA7	1	1	1	70000h–7FFFFh

**Note:** All sectors are 64 Kbytes in size.

### Autoselect Mode

The autoselect mode provides manufacturer and device identification, and sector protection verification, through identifier codes output on DQ7–DQ0. This mode is primarily intended for programming equipment to automatically match a device to be programmed with its corresponding programming algorithm. However, the autoselect codes can also be accessed in-system through the command register.

When using programming equipment, the autoselect mode requires  $V_{ID}$  (11.5 V to 12.5 V) on address pin A9. Address pins A6, A1, and A0 must be as shown in Autoselect Codes (High Voltage Method) table. In addition, when verifying sector protection, the sector

address must appear on the appropriate highest order address bits. Refer to the corresponding Sector Address Tables. The Command Definitions table shows the remaining address bits that are don't care. When all necessary bits have been set as required, the programming equipment may then read the corresponding identifier code on DQ7–DQ0.

To access the autoselect codes in-system, the host system can issue the autoselect command via the command register, as shown in the Command Definitions table. This method does not require  $V_{ID}$ . See "Command Definitions" for details on using the autoselect mode.

**Table 3. Am29F040B Autoselect Codes (High Voltage Method)**

Description	A18–A16	A15–A10	A9	A8–A7	A6	A5–A2	A1	A0	Identifier Code on DQ7–DQ0
Manufacturer ID: AMD	X	X	$V_{ID}$	X	$V_{IL}$	X	$V_{IL}$	$V_{IL}$	01h
Device ID: Am29F040B	X	X	$V_{ID}$	X	$V_{IL}$	X	$V_{IL}$	$V_{IH}$	A4h
Sector Protection Verification	Sector Address	X	$V_{ID}$	X	$V_{IL}$	X	$V_{IH}$	$V_{IL}$	01h (protected)
									00h (unprotected)

## Sector Protection/Unprotection

The hardware sector protection feature disables both program and erase operations in any sector. The hardware sector unprotection feature re-enables both program and erase operations in previously protected sectors.

Sector protection/unprotection must be implemented using programming equipment. The procedure requires a high voltage ( $V_{ID}$ ) on address pin A9 and the control pins. Details on this method are provided in a supplement, publication number 19957. Contact an AMD representative to obtain a copy of the appropriate document.

The device is shipped with all sectors unprotected. AMD offers the option of programming and protecting sectors at its factory prior to shipping the device through AMD's ExpressFlash™ Service. Contact an AMD representative for details.

It is possible to determine whether a sector is protected or unprotected. See "Autoselect Mode" for details.

## Hardware Data Protection

The command sequence requirement of unlock cycles for programming or erasing provides data protection against inadvertent writes (refer to the Command Definitions table). In addition, the following hardware data protection measures prevent accidental erasure or pro-

gramming, which might otherwise be caused by spurious system level signals during  $V_{CC}$  power-up and power-down transitions, or from system noise.

### Low $V_{CC}$ Write Inhibit

When  $V_{CC}$  is less than  $V_{LKO}$ , the device does not accept any write cycles. This protects data during  $V_{CC}$  power-up and power-down. The command register and all internal program/erase circuits are disabled, and the device resets. Subsequent writes are ignored until  $V_{CC}$  is greater than  $V_{LKO}$ . The system must provide the proper signals to the control pins to prevent unintentional writes when  $V_{CC}$  is greater than  $V_{LKO}$ .

### Write Pulse "Glitch" Protection

Noise pulses of less than 5 ns (typical) on OE#, CE# or WE# do not initiate a write cycle.

### Logical Inhibit

Write cycles are inhibited by holding any one of OE# =  $V_{IL}$ , CE# =  $V_{IH}$  or WE# =  $V_{IH}$ . To initiate a write cycle, CE# and WE# must be a logical zero while OE# is a logical one.

### Power-Up Write Inhibit

If WE# = CE# =  $V_{IL}$  and OE# =  $V_{IH}$  during power up, the device does not accept commands on the rising edge of WE#. The internal state machine is automatically reset to reading array data on power-up.

## COMMAND DEFINITIONS

Writing specific address and data commands or sequences into the command register initiates device operations. The Command Definitions table defines the valid register command sequences. Writing **incorrect address and data values** or writing them in the **improper sequence** resets the device to reading array data.

All addresses are latched on the falling edge of WE# or CE#, whichever happens later. All data is latched on the rising edge of WE# or CE#, whichever happens first. Refer to the appropriate timing diagrams in the "AC Characteristics" section.

### Reading Array Data

The device is automatically set to reading array data after device power-up. No commands are required to retrieve data. The device is also ready to read array data after completing an Embedded Program or Embedded Erase algorithm.

After the device accepts an Erase Suspend command, the device enters the Erase Suspend mode. The system can read array data using the standard read timings, except that if it reads at an address within erase-suspended sectors, the device outputs status

data. After completing a programming operation in the Erase Suspend mode, the system may once again read array data with the same exception. See "Erase Suspend/Erase Resume Commands" for more information on this mode.

The system *must* issue the reset command to re-enable the device for reading array data if DQ5 goes high, or while in the autoselect mode. See the "Reset Command" section, next.

See also "Requirements for Reading Array Data" in the "Device Bus Operations" section for more information. The Read Operations table provides the read parameters, and Read Operation Timings diagram shows the timing diagram.

### Reset Command

Writing the reset command to the device resets the device to reading array data. Address bits are don't care for this command.

The reset command may be written between the sequence cycles in an erase command sequence before erasing begins. This resets the device to reading array

data. Once erasure begins, however, the device ignores reset commands until the operation is complete.

The reset command may be written between the sequence cycles in a program command sequence before programming begins. This resets the device to reading array data (also applies to programming in Erase Suspend mode). Once programming begins, however, the device ignores reset commands until the operation is complete.

The reset command may be written between the sequence cycles in an autoselect command sequence. Once in the autoselect mode, the reset command *must* be written to return to reading array data (also applies to autoselect during Erase Suspend).

If DQ5 goes high during a program or erase operation, writing the reset command returns the device to reading array data (also applies during Erase Suspend).

### Autoselect Command Sequence

The autoselect command sequence allows the host system to access the manufacturer and device codes, and determine whether or not a sector is protected. The Command Definitions table shows the address and data requirements. This method is an alternative to that shown in the Autoselect Codes (High Voltage Method) table, which is intended for PROM programmers and requires  $V_{ID}$  on address bit A9.

The autoselect command sequence is initiated by writing two unlock cycles, followed by the autoselect command. The device then enters the autoselect mode, and the system may read at any address any number of times, without initiating another command sequence.

A read cycle at address XX00h or retrieves the manufacturer code. A read cycle at address XX01h returns the device code. A read cycle containing a sector address (SA) and the address 02h in returns 01h if that sector is protected, or 00h if it is unprotected. Refer to the Sector Address tables for valid sector addresses.

The system must write the reset command to exit the autoselect mode and return to reading array data.

### Byte Program Command Sequence

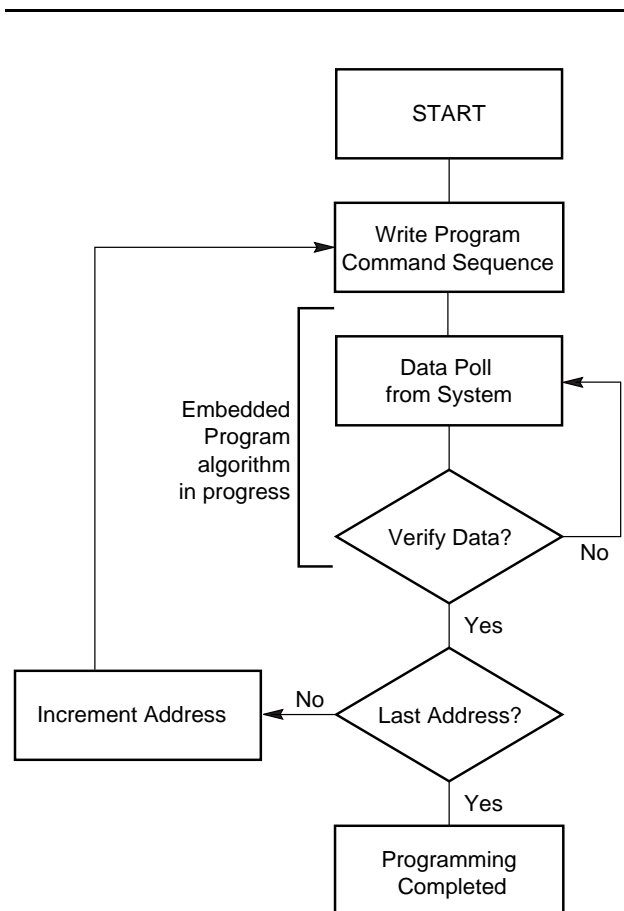
Programming is a four-bus-cycle operation. The program command sequence is initiated by writing two unlock write cycles, followed by the program set-up command. The program address and data are written next, which in turn initiate the Embedded Program algorithm. The system is *not* required to provide further controls or timings. The device automatically provides internally generated program pulses and verify the programmed cell margin. The Command Definitions take

shows the address and data requirements for the byte program command sequence.

When the Embedded Program algorithm is complete, the device then returns to reading array data and addresses are no longer latched. The system can determine the status of the program operation by using DQ7 or DQ6. See "Write Operation Status" for information on these status bits.

Any commands written to the device during the Embedded Program Algorithm are ignored.

Programming is allowed in any sequence and across sector boundaries. **A bit cannot be programmed from a "0" back to a "1"**. Attempting to do so may halt the operation and set DQ5 to "1", or cause the Data# Polling algorithm to indicate the operation was successful. However, a succeeding read will show that the data is still "0". Only erase operations can convert a "0" to a "1".



21445C-6

**Note:** See the appropriate Command Definitions table for program command sequence.

Figure 1. Program Operation